

VEHICLE COLLISION AVOIDANCE SYSTEM

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ABSTRACT

Nowadays, the number of accidents is so high and uncertain. Accidents causes worst damage, serious injury and even death. These accidents are mostly caused by delay of the driver to hit the brake. Preventive measure such as improving visibility, auto headlights, windshield wipers, tire traction, etc. were deployed to reduce the probability of getting into an accident. Now we are at the stage of actively avoiding accidents as well as providing maximum protection to the vehicle occupants and even pedestrians. Hence in this paper, we make an attempt to propose a new automated vehicle collision avoidance system. This project is designed to develop a new system that can solve this problem where drivers may not brake manually but the vehicles can stop automatically due to obstacles by using sensors. Thus, this paper focuses on the development of a sensor based embedded system that can assist the drivers to avoid any sort of collision on the road in order to save the precious lives and also to prevent the financial loss

1.INTRODUCTION OF PROJECT

Collision avoidance systems concentrates on advanced ideas such as pre-crash sensing, an ultrasonic sensor is used to sense the object in front of the vehicle and gives the signal to the microcontroller unit. Based on the signal received from the ultrasonic sensor, the microcontroller unit sends a signal to the braking unit for applying the brake automatically. A collision avoidance system, also known as a pre-crash system, forward collision warning system, or collision mitigating system, is an automobile safety system designed to prevent or reduce the severity of a

collision. It uses radar (all-weather) and sometimes laser (LIDAR) and camera (employing image recognition) to detect an imminent crash. GPS sensors can detect fixed dangers such as approaching stop signs through a location database. Once an impending collision is detected, these systems provide a warning to the driver. When the collision becomes imminent, they take action autonomously without any driver input (by braking or steering or both). Collision avoidance by braking is appropriate at low vehicle speeds (e.g. below 50 km/h (31 mph)), while collision avoidance by steering may be more appropriate at higher vehicle speeds if lanes are clear. Cars with collision avoidance may also be equipped with adaptive cruise control, using the same forward-looking sensors According to the global road safety partnership annual report 2014 [1], as many as 1.24 million people died each year due to various road accidents occurring throughout the world. Apart from the above-mentioned death toll, almost 50 million people become victim of critical life-altering injuries. This is a global humanitarian disaster and this is 8th leading cause of the death globally. According to the World Health Organization, road traffic injuries caused an estimated 1.35 million deaths worldwide in the year 2016.[6] According to the 2013 global survey of traffic collisions by the UN World Health Organization, India suffered a road fatality rate of 16.6 per 100,000 people in 2013. India's average traffic

collision fatality rate was similar to the world average rate of 17.4 deaths per 100,000 people, less than the low-income countries which averaged 24.1 deaths per 100,000, and higher than the high-income countries which reported the lowest average rate of 9.2 deaths per 100,000 in 2013.[5]

II. LITERATURE SURVEY

[1.1] Predictive vehicle collision avoidance system using raspberry-bi it seemed like to avoid accidents in the blind spot area using ultrasonic sensor using raspberry-bi module. The ultrasonic sensor works like radar system to detect the obstacles in the blind spot that can Cause the accident but it is cheaper than it. In addition to that the ultrasonic sensor is used to measure the distance between the vehicle and the obstacles and saved the distance safe before fatalities happened and alerting the driver before the accident using two ways visualization using light emitting diode (LED) and make a sound using buzzer and the driver alone apply the brake or steering to controlling on the speed. The main advantage of ultrasonic sensor is that it provides highest reliability in getting proximity and has lesser absorption than RF and IR frequencies.

[1.2] Advanced Accident Avoidance System for Automobiles. This paper discussed the most important factors of accident due to the intersection accident and the bad weather and this whether to some extent either the heavy rain, huge ice or high darkness. Indeed, this bad weather conditions the driver feel very harsh to drive the vehicle and can't controlling the car. In this paper there are for types of sensors such as lm35 temperature sensor and humidity sensor and those sensors are used to check the weather states and alert the driver if any thinks happen in the weather. And there are a substation number of ultrasonic sensors to detect the near car and infrared sensors used to detect the forward cars

by using burst of light to measure the cars speed, distance and position those sensors were fixed in the both car sides and in the forward of the vehicle to avoid all the cars and any barrier and alert the driver. This system was provided by Global System for Mobile communications (GSM) and Global Positioning System (GPS) module. If the accident were happened then the system automatically takes position of the car and sends it to the police office and the driver family to save the driver and passenger's health.

[1.3] Internet of Car: Accident Sensing, Indication and Safety with Alert system. In this paper we are discussing how to use ultrasonic sensor and radar system and laser to detect the obstacles such as humans, animals or vehicles and send the car and driver information to the police and their siblings and controlling of the brake system, the steering system and doors. And determine the accident coordinates and send the data via GSM module in addition to that the data can send the data via Wi-Fi to the twitter. Actually, the main technology used is Obstacle detection & indication sensor in this method we use the photoelectric sensor it mainly consists of transmitter and receiver. In the two side of cars there are two sensors to detect the obstacles. The indicator used the redlight emitting diode (LED) when it finds obstacles. Subsequently the second method is used is passive infrared (PIR) sensor or we can say human detection sensors. The importance of this sensor to detect the human near the car and give the car order to avoid this human. To detect the accident here they used complex three axis accelerometer. This sensor mainly detects the accident when the car deviate by angle from the road in addition to that the system were provided by relay circuit to protect the car from battery ignition when the accident occurs and this system uses GUS designed by

android platform to monitor and tracking the vehicle.

[1.4] Vehicle collision avoidance system prototype that will alert drivers to their surroundings and potentially hazardous driving situations. This system is needed to reduce the number of vehicle accidents on the road. Such a system would lead to improved efficiency of the road usage and limit human as well as economic losses. The proposed system will use ultrasonic sensors to provide blind spot coverage, while utilizing long-range radar to detect possible frontal collisions. The system will be implementable on a variety of standard cars with easy installation. While the system will not provide any autonomous action to avoid collisions, it will warn the driver through both audible and visual warnings. The system will be evaluated through rigorous testing in order to develop an algorithm that encompasses most of the countless circumstances encountered on the road. Once the system is implemented, the system will accurately detect the presence of surrounding vehicles with minimal false positives and the driver will be alerted to any possible accident, giving him or her adequate time to respond

III. DESIGN OF HARDWARE

This chapter briefly explains about the Hardware. It discuss the circuit diagram of each module in detail.

ARDUINO UNO

The Arduino Uno is a microcontroller board based on the ATmega328 (datasheet). It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button. It contains everything needed to support the

microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started.

The Uno differs from all preceding boards in that it does not use the FTDI USB-to-serial driver chip. Instead, it features the Atmega16U2 (Atmega8U2 up to version R2) programmed as a USB-to-serial converter. Uno board has a resistor pulling the 8U2 HWB line to ground, making it easier to put into DFU mode. Arduino board has the following new features:

- 1.0 pin out: added SDA and SCL pins that are near to the AREF pin and two other new pins placed near to the RESET pin, the IOREF that allow the shields to adapt to the voltage provided from the board. In future, shields will be compatible both with the board that use the AVR, which operate with 5V and with the Arduino Due that operate with 3.3V. The second one is a not connected pin, that is reserved for future purposes.
- Stronger RESET circuit.
- Atmega 16U2 replace the 8U2.

"Uno" means one in Italian and is named to mark the upcoming release of Arduino 1.0. The Uno and version 1.0 will be the reference versions of Arduino, moving forward. The Uno is the latest in a series of USB Arduino boards, and the reference model for the Arduino platform; for a comparison with previous versions, see the index of Arduino boards.

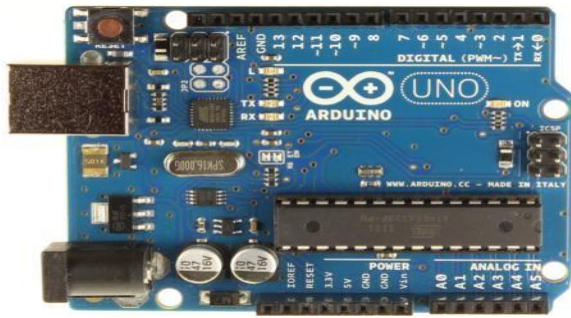


Fig: ARDUINO UNO

POWER SUPPLY:

The power supplies are designed to convert high voltage AC mains electricity to a suitable low voltage supply for electronic circuits and other devices. A power supply can be broken down into a series of blocks, each of which performs a particular function. A d.c power supply which maintains the output voltage constant irrespective of a.c mains fluctuations or load variations is known as “Regulated D.C Power Supply”.

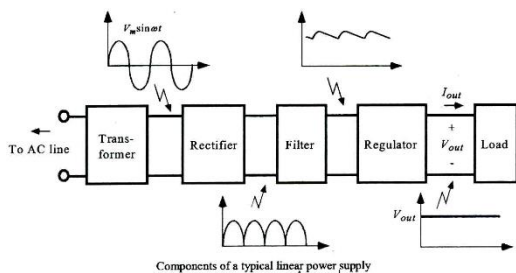


Fig: Block Diagram of Power Supply

LCD DISPLAY

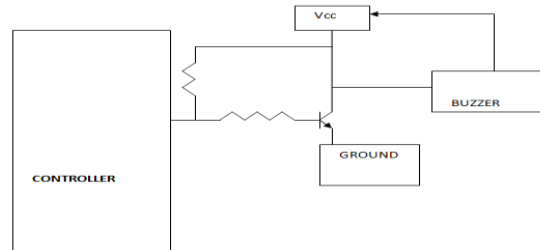
A model described here is for its low price and great possibilities most frequently used in practice. It is based on the HD44780 microcontroller (Hitachi) and can display messages in two lines with 16 characters each. It displays all the alphabets, Greek letters, punctuation marks, mathematical symbols etc. In

addition, it is possible to display symbols that user makes up on its own. Automatic shifting message on display (shift left and right), appearance of the pointer, backlight etc. are considered as useful characteristics.



Fig: LCD BUZZER

Digital systems and microcontroller pins lack sufficient current to drive the circuits like relays, buzzer circuits etc. While these circuits require around 10milli amps to be operated, the microcontroller’s pin can provide a maximum of 1-2milli amps current. For this reason, a driver such as a power transistor is placed in between the microcontroller and the buzzer circuit.



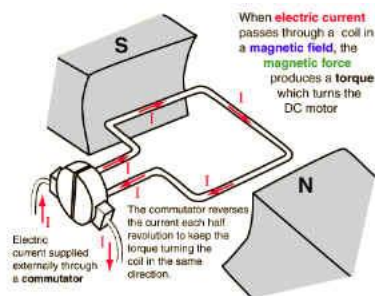
L293D:

The L293 and L293D are quadruple high-current half-H drivers. The L293 is designed to provide bidirectional drive currents of up to 1 A at voltages from 4.5 V to 36 V. The L293D is designed to provide bidirectional drive currents of up to 600-mA at voltages from 4.5 V to 36 V. Both devices are designed to drive inductive loads such as relays, solenoids, dc and bipolar stepping motors, as well as other high-current/high-voltage loads in positive-supply

applications. All inputs are TTL compatible. Each output is a complete totem-pole drive circuit, with a Darlington transistor sink and a pseudo-Darlington source. Drivers are enabled in pairs, with drivers 1 and 2 enabled by 1,2EN and drivers 3 and 4 enabled by 3,4EN. When an enable input is high, the associated drivers are enabled, and their outputs are active and in phase with their inputs. When the enable input is low, those drivers are disabled, and their outputs are off and in the high-impedance state. With the proper data inputs, each pair of drivers forms a full-H (or bridge) reversible drive suitable for solenoid or motor applications.

DC MOTOR

A DC motor is designed to run on DC electric power. Two examples of pure DC designs are Michael Faraday's homopolar motor (which is uncommon), and the ball bearing motor, which is (so far) a novelty. By far the most common DC motor types are the brushed and brushless types, which use internal and external commutation respectively to create an oscillating AC current from the DC source -- so they are not purely DC machines in a strict sense.



Ultrasonic sensor:

The sensor is primarily intended to be used in security systems for detection of moving objects, but can be effectively involved in intelligent

children's toys, automatic door opening devices, and sports training and contact-less-speed measurement equipment.

Modern security systems utilize various types of sensors to detect unauthorized object access attempts. The sensor collection includes infrared, microwave and ultrasound devices, which are intended to detect moving objects. Each type of sensor is characterized by its own advantages and drawbacks. Microwave sensors are effective in large apartments because microwaves pass through dielectric materials. But these sensors consist of expensive super-high frequency components and their radiation is unhealthy for living organisms.

Infrared sensors are characterized by high sensitivity, low cost and are widely used. But, these sensors can generate false alarm signals if heating systems are active or temperature change speed exceeds some threshold level. Moreover, infrared sensors appreciably lose sensitivity if small insects penetrate the sensor lens. Ultrasound motion detection sensors are characterized by small power consumption, suitable cost and high sensitivity. That it why this kind of sensor is commonly used in home, office and car security systems. Existing ultrasound sensors consist of multiple passive and active components and are relatively complicated for production and testing. Sensors often times require a laborious tuning process.

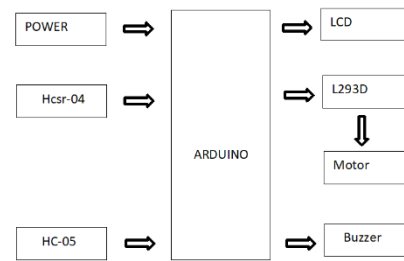
Bluetooth

Bluetooth is a wireless protocol utilizing short-range communications technology facilitating data transmission over short distances from fixed and/or mobile devices, creating wireless personal area networks (PANs). The intent behind the development of Bluetooth was

the creation of a single digital wireless protocol, capable of connecting multiple devices and overcoming issues arising from synchronization of these devices. Bluetooth uses a very robust radio technology called frequency hopping spread spectrum. It chops up the data being sent and transmits chunks of it on up to 75 different frequencies. In its basic mode, the modulation is Gaussian frequency shift keying (GFSK). It can achieve a gross data rate of 1 Mb/s. Bluetooth provides a way to connect and exchange information between devices such as mobile phones, telephones, laptops, personal computers, printers, GPS receivers, digital cameras, and video game consoles over a secure, globally unlicensed Industrial, Scientific, and Medical (ISM) 2.4 GHz short-range radio frequency bandwidth. The Bluetooth specifications are developed and licensed by the Bluetooth Special Interest Group (SIG). The Bluetooth SIG consists of companies in the areas of telecommunication, computing, networking, and consumer electronics.

Bluetooth is a standard and communications protocol primarily designed for low power consumption, with a short range (power-class-dependent: 1 meter, 10 meters, 100 meters) based on low-cost transceiver microchips in each device. Bluetooth enables these devices to communicate with each other when they are in range. The devices use a radio communications system, so they do not have to be in line of sight of each other, and can even be in other rooms, as long as the received transmission is powerful enough. Bluetooth device class indicates the type of device and the supported services of which the information is transmitted during the discovery process.

IV. BLOCK DIAGRAM



V. CONCLUSION

Collision avoidance system is designed and mounted on a very simple and easily understandable model. The sensors can read distances that are at shorter range accurately. The system takes action automatically without any driver input. Hence this automatic braking system can stop the car to avoid an accident.

FUTURE SCOPE

1. With the blooming of IoT (Internet of Things) tracking of packages becomes easier. Using the internet instead of GSM services also reduces the cost for communication.
2. The box could be built inside the wall so that only receiving compartment lid is visible to outside world thus providing an extra security to the package and the box itself.
3. The box can be paired with artificial intelligence like Alexia or Google Assistant.
4. Further improvisation could be made by adding biometric verification at the customer premises.

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